# GR — Exercise sheet 3

Francesco Zappa

[francesco.zappa@uni-jena.de, Abbeanum, office 219] (Return date: 11.11.19)

01.11.2019

# **Special Relativity**

## **Exercise 1.1:** Hyperbolic orthogonality

Two four-vectors  $a^{\mu}$ ,  $b^{\nu}$  are orthogonal if  $a_{\mu}b^{\mu} = 0$ . Show that (a) the sum of two vectors can be spacelike, null or timelike independently of the nature of the vectors, and (b) non-spacelike vectors which are orthogonal to a given nonzero null vector, must be multiples of the null vector. (c) Find four linearly independent null vectors in the Minkowski space.

## Exercise 1.2: Having fun with indices

Imagine we have a tensor  $X^{\mu\nu}$  and a vector  $V^{\mu}$ , with components

$$X^{\mu\nu} = \begin{pmatrix} 2 & 0 & 1 & 0 \\ -2 & 2 & 2 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & -2 \end{pmatrix}_{\mu\nu}, \qquad V^{\mu} = (-2, -1, 0, 2)_{\mu}. \tag{1}$$

Defined in the Minkowki spacetime, where the metric tensor is  $\eta_{\mu\nu} = diag(-1, 1, 1, 1)$ . Using the metric tensor to raise/lower the indices  $(X_{\mu\nu} = \eta_{\mu\rho}\eta_{\nu\sigma}X^{\rho\sigma})$ , calculate the components of the following quantities:

- (a)  $X^{\mu}_{\ \nu}$
- (b)  $X_{\mu}^{\ \nu}$
- (c)  $X^{(\mu\nu)}$
- (d)  $X_{[\mu\nu]}$
- (e)  $X^{\lambda}_{\ \lambda}$
- (f)  $V^{\mu}V_{\mu}$
- (g)  $V_{\mu}X^{\mu\nu}$

## Manifolds

#### Exercise 2.1: Curves in a manifold

In Euclidean three-space, let p be the point with coordinates (x, y, z) = (1, 0, -1). Consider the following curves:

$$\begin{aligned} x^{i}(\lambda) &= (\lambda, \ (\lambda - 1)^{2}, \ -\lambda) \\ x^{i}(\mu) &= (\cos \mu, \ \sin \mu, \ \mu - 1) \\ x^{i}(\sigma) &= (\sigma^{2}, \ \sigma^{3} + \sigma^{2}, \ \sigma). \end{aligned}$$

- (a) Verify that all the curves above pass through p.
- (b) Calculate the components of the tangent vectors to the curves at p in the coordinate basis  $\{\partial_x, \partial_y, \partial_z\}$ .
- (c) Let  $f = x^2 + y^2 yz$ . Calculate  $df/d\lambda$ ,  $df/d\mu$ ,  $df/d\sigma$ .

### Exercise 2.2: Infinite cylinder as manifold

Consider the infinite cylinder with the main axis coincident with the x-axis. It can be thought as the set  $C \equiv \mathbb{S}^1 \times \mathbb{R} \equiv \{(x, y, z) \in \mathbb{R}^3 : y^2 + z^2 = 1\}$ . A subset of C can be mapped to a subset of  $\mathbb{R}^2$  using the following map:

$$\psi(x, y, z) = e^x(y, z). \tag{2}$$

Show that C is a manifold.