

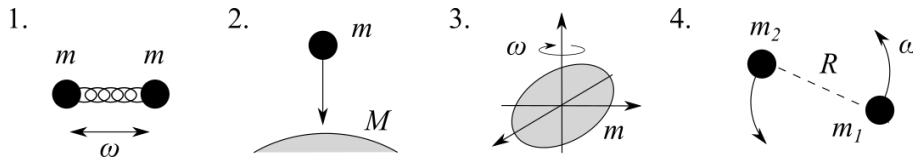
Gravitational waves — Exercise sheet n.1

Solutions

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Exercise 1.1: Quadrupole approximation



Consider the following sources of gravitational radiation (see Fig. 1):

1. Two point particles with mass m oscillating with pulsation ω along a fixed axis;
2. Free-falling point-particle with mass m in a Newtonian gravitational field (of mass M);
3. Ellipsoid (with semi-axes a , b , c) rotating around one of its principal axis with frequency ω ;
4. Two point particles (with different masses m_1 , m_2) in Newtonian circular orbit.

For these cases, compute:

- Inertia tensor of the source,

$$Q^{ij}(t) \equiv I^{ij} - \frac{1}{3}\delta^{ij} I^{kk} = \int d^3x \rho(t, \vec{x}) \left(x^i x^j - \frac{1}{3}r^2 \delta^{ij} \right). \quad (1)$$

Note that I_{ij} is the standard inertia tensor, while Q_{ij} is the trace-free inertia tensor.

- Gravitational wave emitted in quadrupole approximation in the TT gauge,

$$h_{ij}^{\text{TT}}(t, \vec{x}) = \frac{2G}{r c^4} \Lambda_{ij,mn}(\theta, \phi) \ddot{Q}_{mn}(t - r/c), \quad (2)$$

where $\Lambda_{ij,mn}$ is the TT projector.

Solution ??

1. Oscillating particles:

- In the center of mass frame, the equation of motion can be reduced to the dynamics of a single particle of mass $\mu = m/2$. Then, fixing the oscillation along the z axis, we can write

$$\ddot{\delta} + \omega^2 \delta = 0, \quad (3)$$

where $\delta = z_1 - z_2$ is the distance between the two particles. From Eq. (3), it follows the equation of motion for $\delta(t) \propto \cos(\omega t)$. Then, the inertia tensor of the source in the center of mass frame can be computed as

$$I_{ij} = \mu x_i(t) x_j(t). \quad (4)$$

The only non-zero component of I_{ij} correspond to $i = j = 3$ since the motion is constrained on the z axis (by construction). This form can be easily mapped into its trace-free version, which takes a diagonal form, $Q_{11} = Q_{22} = -(1/3)m\delta^2(t)$ and $Q_{33} = (2/3)m\delta^2(t)$.

- From this result, we can derive the gravitational strain h_{ij}^{TT} in the TT gauge as

$$h_+ = -\frac{G}{rc^4} \sin^2 \theta \ddot{I}_{11}(t) \quad h_\times = 0. \quad (5)$$

Note that the radiate GW will be a monochromatic signal with frequency $\omega_{gw} = 2\omega$ only if the rest separation between the particle is zero. Otherwise, the GW spectrum will be characterized by two peaks located at frequency ω and 2ω .

2. Free-falling particle:

- Taking the z -axis parallel to the velocity of the particle, In the Newtonian approximation, we can write

$$\frac{1}{2}m\dot{z}^2 - \frac{GMm}{z} = 0, \quad (6)$$

where \dot{z} represent the derivative of z with respect to time (i.e. the velocity). Then it follows,

$$\dot{z} = c\sqrt{\frac{R_s}{z}} \quad \Rightarrow \quad z(t) \propto t^{2/3}, \quad (7)$$

where $R_s = 2GM/c^2$ is the Schwarzschild radius of the central object. Now we can compute the inertia tensor for the free-falling particle as

$$I_{ij} = m x_i(t) x_j(t), \quad (8)$$

where the only non-vanishing term is $I_{33} = mz^2(t)$. This form can be easily mapped into its trace-free version, which takes a diagonal form, $Q_{11} = Q_{22} = -(1/3)mz^2(t)$ and $Q_{33} = (2/3)mz^2(t)$.

- From this result, we can derive the gravitational strain h_{ij}^{TT} in the TT gauge as

$$h_+ = -\frac{G}{rc^4} \sin^2 \theta \ddot{I}_{33}(t) \quad h_\times = 0. \quad (9)$$

3. Rotating ellipsoid:

- We can write the inertia tensor for a non-rotating ellipsoid (in a Cartesian frame with coordinates parallel to the axes of the ellipsoid) as

$$I_{11} = \frac{m}{5} (b^2 + c^2), \quad I_{22} = \frac{m}{5} (a^2 + c^2), \quad I_{33} = \frac{m}{5} (a^2 + b^2), \quad (10)$$

and the other components are zero. If the body rotates with angular velocity ω around the z -axis then we have

$$I'_{ij} = \mathcal{R}_{im} \mathcal{R}_{jn} I_{mn}, \quad (11)$$

where \mathcal{R}_{ij} is the matrix representation of the rotation $\mathcal{R}(\omega t, \hat{z})$ of an angle ωt around the z -axis. Then we get

$$\begin{aligned} I'_{11} &= I_{11} \cos^2(\omega t) + I_{22} \sin^2(\omega t) = 1 + \frac{I_{11} - I_{22}}{2} \cos(2\omega t), \\ I'_{12} &= \frac{I_{11} - I_{22}}{2} \sin(2\omega t), \\ I'_{22} &= I_{11} \sin^2(\omega t) + I_{22} \cos^2(\omega t) = 1 - \frac{I_{11} - I_{22}}{2} \cos(2\omega t), \\ I'_{33} &= I_{33}, \end{aligned} \quad (12)$$

while $I'_{13} = I'_{23} = 0$. Then, observing that the trace of I_{ij} is invariant under rotations, we can write the mass momenta as $Q_{ij} = -I'_{ij} + c_{ij}$ where c_{ij} are constant terms which will vanish after the derivation. Therefore,

$$\begin{aligned} Q_{11} &= -\frac{I_{11} - I_{22}}{2} \cos(2\omega t) + \text{constant}, \\ Q_{12} &= -\frac{I_{11} - I_{22}}{2} \sin(2\omega t) + \text{constant}, \\ Q_{22} &= +\frac{I_{11} - I_{22}}{2} \cos(2\omega t) + \text{constant}, \end{aligned} \quad (13)$$

- Now let us compute the GW received by an observer at distance r , whose line-of-sight makes an angle θ with the direction of spin of the star (without loss of generality we set $\phi = 0$). Inserting Eq. (13) into the definition of h_{ij}^{TT} we get

$$\begin{aligned} h_+ &= \frac{1}{r} \frac{4G\omega^2}{c^4} (I_{11} - I_{22}) \frac{1 + \cos^2 \theta}{2} \cos(2\omega t), \\ h_\times &= \frac{1}{r} \frac{4G\omega^2}{c^4} (I_{11} - I_{22}) \cos \theta \sin(2\omega t). \end{aligned} \quad (14)$$

4. Binary system:

- Consider two point particles with masses m_1 and m_2 in Newtonian circular orbit at distance R . We choose the frame so that it is centered in the center of mass (CM) and the orbit lies in the xy -plane and the trajectory is given by

$$\begin{aligned}x(t) &= R \cos(\omega t + \pi/2), \\y(t) &= R \sin(\omega t + \pi/2), \\z(t) &= 0,\end{aligned}\tag{15}$$

where we assume $\phi_0 = \pi/2$ (since it is a useful choice). We define the total mass of the system as $M = m_1 + m_2$ and the reduced mass of the system, $\mu = m_1 m_2 / M$. From the definition of mass momenta, in the CM frame, we get

$$Q_{ij} = \mu x_i(t) x_j(t),\tag{16}$$

where

$$\begin{aligned}Q_{11} &= \mu R^2 \frac{1 - \cos(2\omega t)}{2}, \\Q_{22} &= \mu R^2 \frac{1 + \cos(2\omega t)}{2}, \\Q_{12} &= -\frac{1}{2} \mu R^2 \sin(2\omega t),\end{aligned}\tag{17}$$

while the other components vanish. Therefore,

$$\begin{aligned}\ddot{Q}_{11} &= -\ddot{Q}_{22} = 2\mu R^2 \omega^2 \cos(2\omega t), \\ \ddot{Q}_{12} &= 2\mu R^2 \omega^2 \sin(2\omega t).\end{aligned}\tag{18}$$

- Using Eq. (18) in the definition of h_{ij}^{TT} in the quadrupole approximation we get

$$\begin{aligned}h_+(t) &= \frac{1}{r} \frac{4G\mu R^2 \omega^2}{c^4} \frac{1 + \cos^2 \theta}{2} \cos(2\omega t + 2\phi), \\ h_\times(t) &= \frac{1}{r} \frac{4G\mu R^2 \omega^2}{c^4} \cos \theta \sin(2\omega t + 2\phi).\end{aligned}\tag{19}$$